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differential geometry,
but also how to define,
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$y(t), z=z(t)$,
where $t \in [a, b]$, and the e
quations $x=x(t), y=y(t), z=z(t)$ are called parametric

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equationsof a curve .

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regular curve is
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These are all the geodesics since now for any point and any direction, there is a unique such curve.

2.9.2 Geodesics on surfaces of revolution.

We look at the surface of revolution $\mathbf{r}(u;v) = (f(u)\cos v; f(u)\sin v; g(u))$; with $f^2 u + g^2 u = 1$ and $f > 0$. So $I = du^2 +$

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$f_2(u)dv_2$: Hence two geodesic equations $d/dt (Eu_+ + Fv_+) = 1/2 (E$

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Differential geometry is a mathematical discipline that uses the techniques of differential calculus, integral calculus, linear algebra

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and multilinear algebra to study problems in geometry. The theory of plane and space curves and surfaces in the three-dimensional Euclidean space formed the basis for development of differential geometry during the 18th century and the 19th century.

Since the late 19th century, differential geometry has grown

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Geodesics are curves on the surface which satisfy a certain second-order ordinary differential equation which is specified by the first fundamental form. They are very directly connected to the study of lengths of curves; a geodesic of sufficiently short length will always

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be the curve of shortest length on the surface which connects its two endpoints. Thus, geodesics are fundamental to the optimization problem of determining the shortest path between two given points on a regular surface.

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On the other hand, the use of surface theory is extremely essential in studying manifolds of positive curvatures, pseudo-holomorphic curves in symplectic manifolds etc, which are all active research directions in modern differential geometry. Similar special phenomenon occurs

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